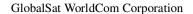
GLOBALSAT GPS+BDS Engine Board

Hardware Data Sheet

Product No: MT-5110B

Version 1.3





16F., No. 186, Jian-Yi Road, Chung-Ho City, Taipei

Hsien 235, Taiwan

Tel: 886-2-8226-3799 Fax: 886-2-8226-3899

E-mail: service@globalsat.com.tw
Website: www.globalsat.com.tw

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2013/08/02 Ray Mason



Product Description

Product Description

MT-5110B is a compact, high performance, and low power consumption GPS+BDS engine board. The chipset is powered by MediaTek, it can provide you with superior sensitivity and performance even in urban canyon and dense foliage environment. The miniature size makes the module easy and the best choice to integrate into portable applications such as DSC, cellular phone, PMP, and gaming devices. MT-5110B is suitable for the following applications:

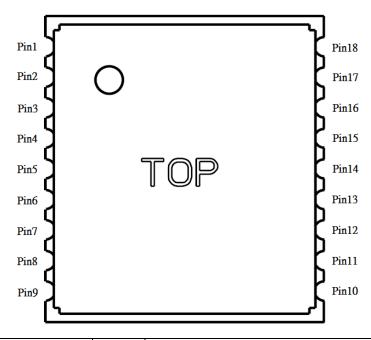
- Automotive navigation
- Personal positioning
- Fleet management
- Mobile phone navigation
- Marine navigation

Product Features

- MediaTek high sensitivity solution
- Support 33 tracking / 99 acquisition-channel GPS/BDS receiver
- Very high sensitivity (Tracking Sensitivity: -165dBm)
- Extremely fast TTFF (Time To First Fix) at low signal level
- Support UART(bidirectional transmission) interface
- Support Serial port NMEA output.
- Built-in LNA
- Compact size (10.1mm x 9.7mm x 2.4mm) suitable for space-sensitive application
- One size component, easy to mount on another PCB board
- Support NMEA 0183 V4.0 (GGA, GSA, GSV, RMC, VTG, GLL, ZDA)
- Supports WASS/EGNOS/MSAS/GAGAN (depends on firmware setting)



Product Pin Description



| PIN Number(s) | Name | Туре | Description | Note |
|---------------|-----------|------|------------------------------------------------|------|
| | | 0 | This is the main transmits channel for | |
| | | | outputting navigation and measurement data | |
| 2 | TXD | | to user's navigation software or user written | |
| | | | software. Baud rate based on firmware | |
| | | | setting, Output TTL level 2.8V. | |
| | | | This is the main receive channel for receiving | |
| 3 | RXD | | software commands to the engine board from | |
| 3 | RXD | ı | MTK software or from user written software. | |
| | | | Baud rate based on firmware setting. | |
| | TIMEPULSE | 0 | This pin provides one pulse-per-second | |
| 4 | | | output from the board, which is synchronized | |
| | | | to GPS time. If do not use it, Just NC. | |
| | VBAT | Р | This is the power input for the SRAM and | |
| | | | RTC. To achieve the faster start-up offered | |
| 6 | | | by a hot or warm start, a backup power must | |
| | | | be connected. The power voltage should be | |
| | | | between 2.5V and 4.3V. | |
| 5,7,13,15,16 | RESERVED | | MT-5110B reserved pin, just NC. | |
| ,17,18 | | | 31.32 13331734 pm, jast 173. | |
| 8 | VCC | Р | This is the main power supply to the engine | |
| J | | ' | board. (3.3Vdc to 4.3Vdc) | |

MT-5110B High Performance GPS+BDS Engine Board



| 1,10,12 | GND | P Ground | | |
|---------|------------|----------|-------------------------------------------------|--|
| 9 | DECET | I | This pin is input low active. This Module has | |
| 9 | RESET | | internal Power on Reset circuit. | |
| | | I | This pin receives signal of GPS/BDS analog | |
| | | | via external antenna. It has to be a controlled | |
| 4.4 | DE IN | | impedance trace at 50ohm. Do not have RF | |
| 11 | 11 RF_IN | | traces closed the other signal path and | |
| | | | routing it on the top layer. Keep the RF traces | |
| | | | as short as possible. | |
| 1.4 | 14 VCC_RF | 0 | This pin can supply external active antenna | |
| 14 | | | power 2.8V. If do not use it, just NC. | |



Electrical Specification

Absolute Maximums Ratings

| Parameter | Min. | Тур. | Max. | Conditions | Unit | |
|-------------------------------|------|-------|------|------------|------|--|
| Power | | | | | | |
| Power supply voltage(VCC) | 3.3 | 3.3 | 4.3 | | ٧ | |
| Backup battery supply | 2.5 | | 4.3 | | ٧ | |
| VCC_RF output voltage | | VCC | | | | |
| Main power supply Current | | 37 | | 3.3V | mA | |
| Backup battery supply Current | 4.5 | 5 | 5.5 | 3.3V | uA | |
| RF Input | | | | | | |
| Input Impedance | | 50 | | | Ω | |
| Operating Fraguency | | 1.575 | | | GHz | |
| Operating Frequency | | 1.561 | | | GHZ | |

DC Electrical characteristics

| Parameter | Symbol | Min. | Тур. | Max. | Conditions | Units |
|-------------------------------|------------------------|------|------|------|------------|-------|
| I/O Low Level Output Voltage | Vol | | | 0.42 | | V |
| I/O High Level Output Voltage | Vон | 2.38 | | | | V |
| I/O Low Level Input Voltage | VIL | -0.3 | | 0.7 | | V |
| I/O High Level Input Voltage | Vih | 2.1 | | 3.6 | | V |
| TXD Output Voltage | V _{TO} | 2.52 | 2.8 | 3.08 | | V |
| RXD Input Voltage | V_{RI} | | | 3.6 | | V |
| High Level Output Current | І он | | 2 | | | mA |
| Low Level Output Current | lol | | 2 | | | mA |
| VCC_RF | Vo | | 2.8 | | | V |
| VCC_RF Output Current | Voc | | 7 | | | mA |

Environmental Characteristics

| Parameter | Min | Тур | Max | Unit |
|-----------------------|-----|-----|-----|------------------|
| Humidity Range | 5 | | 95 | % non-condensing |
| Operation Temperature | -40 | 25 | 85 | $^{\circ}$ |
| Storage Temperature | -40 | | 85 | $^{\circ}$ C |

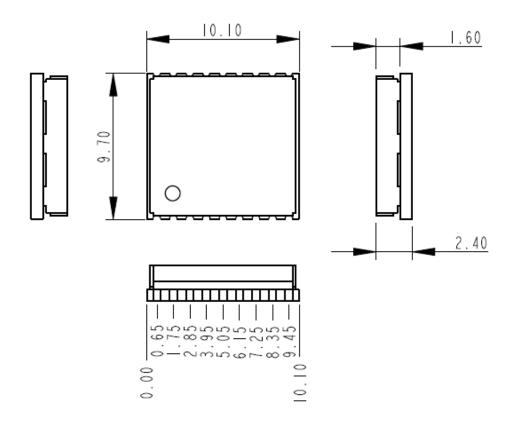


Receiver Performance

| Sensitivity ¹ | Chipset Tracking: | -165dBm | |
|-------------------------------------------|----------------------------------------------|----------------|--|
| Sensitivity | Chipset Autonomous acquisition : | -148 dBm | |
| | Cold Start – Autonomous | < 35s | |
| Time-To-First-Fix ² | Warm Start – Autonomous | < 35s | |
| | Hot Start – Autonomous | < 1s | |
| Horizontal Position Accuracy ³ | Autonomous | < 3m (2D RMS) | |
| Fiorizontal Fosition Accuracy | SBAS | <2.0m | |
| Velocity Accuracy ⁴ | Speed | < 0.01 m/s | |
| Velocity Accuracy | Heading | < 0.01 degrees | |
| Reacquisition | 0.1 second, average | | |
| NMEA Update Rate | Output data format based on firmware setting | | |
| Maximum Altitude | < 18,000 meter | | |
| Maximum Velocity | < 515 meter/ second | | |
| Maximum Acceleration | < 4G | | |



Package Dimensions

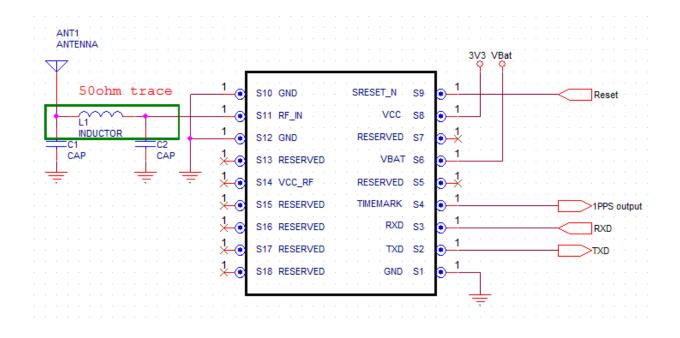


| Туре | 18-pin stamp holes |
|------------|----------------------------------|
| Dimensions | 10.1 mm * 9.7 mm * 2.4 mm ±0.2mm |

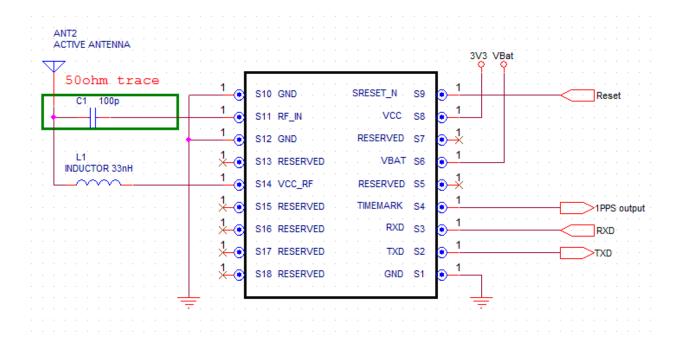


Application

Application circuit with passive antenna



Application circuit with active antenna





GPS/BDS Active Antenna Specifications (Recommendation)

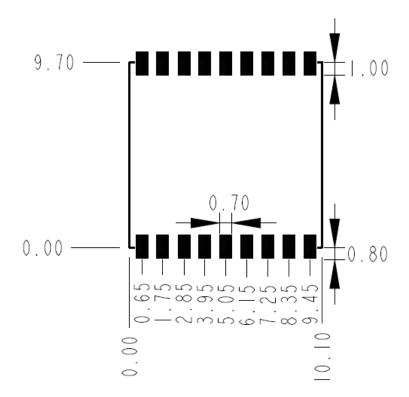
| Frequency: | 1575.42 + 2MHz | Amplifier Gain: | 18~22dB Typical | |
|-------------------|-----------------|------------------------|-----------------|--|
| r requericy. | 1561.098 + 2MHz | Ampililei dairi. | | |
| Axial Ratio: | 3 dB Typical | Output VSWR: | 2.0 Max. | |
| Output Impedance: | 50Ω | Noise Figure: | 2.0 dB Max | |
| Polarization: | RHCP | Antenna Input Voltage: | 2.85V (Typ.) | |

NOTE:

1. VCC_RF: MT-5110B provides power 2.8V to external active antenna



Recommended Layout PAD



Unit: mm

Tolerance: 0.1mm

PCB Layout Recommend

Do not routing the other signal or power trace under the engine board.

RF:

This pin receives signal of GPS/BDS analog via external active antenna. It has to be a controlled impedance trace at 50ohm.

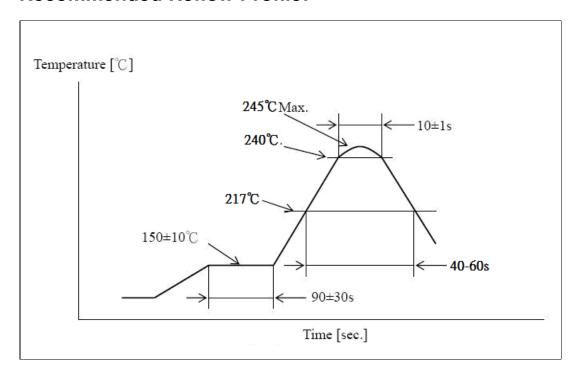
Do not place the RF traces close to the other signal path and not routing it on the top layer. Keep the RF traces as short as possible.

Antenna:

Keep the active antenna on the top of your system and confirm the antenna radiation pattern axial ratio power gain noise figure VSWR are correct when you Setup the antenna in your case.



Recommended Reflow Profile:



Pre heating temperature: $150\pm10[^{\circ}\mathbb{C}]$ Pre heating time: $90\pm30[\sec.]$ Heating temperature: $240\pm5[^{\circ}\mathbb{C}]$ Heating time: $10\pm1[\sec.]$



Appendix

Label Artwork

A: GLOBALSAT

B: Module Info

XX

SX = SiRF

MX = MTK

XG =GPS+GLONASS

XB =GPS+BDS

XC & XS=GPS

XXXX: IC Type & Date code

C: Bar code

D: Serial Number

E: First pin Mark





Reversion history

| Reversion | Date | Name | Status / Comments |
|-----------|-----------|-------|----------------------------------|
| V1.0 | 2013/7/2 | Mason | Initial Version |
| V1.1 | 2013/7/24 | Mason | Modify 3.3V power consumption |
| V1.2 | 2013/8/2 | Mason | Modify VCC & VBAT power ratings. |
| V1.3 | 2014/1/14 | Mason | Modify Label Artwork |
| | | | |